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[Hierarchical Graphs for Graph Grammars \(Extended Abstract\) - Michael Himsolt \(Correct\)](#)
of nodes, and .By explicit declaration of **hierarchy levels**. Representations of the graph where nodes, and .By explicit declaration of **hierarchy levels**. Representations of the graph where parts of the above open or below closed are invisible. Among any **path** from a root to a leaf in T, there may be at most
www.fmi.uni-passau.de/archive/archive.theory/ftp/graphed/papers/HGraph.ps.gz

[The Web and Exerquiz Packages - Manual of Usage - Story \(1999\) \(Correct\)](#)
option The latexoc option 2.4. **Navigational Aids A Navigational Bar** Direction
option 2.4. **Navigational Aids A Navigational Bar** Direction Icons 3. The Exerquiz Package 3.1.
Packages Manual of Usage D. P. Story Directory **Table** of Contents. Begin Article. Copyright c
online.redwoods.cc.ca.us/instruct/darnold/StaffDev/Workshop/webeqman.pdf

[The Web and Exerquiz Packages Manual of Usage - Story \(1999\) \(Correct\)](#)
2.3.4 The latexoc option .6 2.4 **Navigational Aids** .6 2.4.1 A
Aids .6 2.4.1 A **Navigational Bar** .6 2.4.2 Direction Icons
Last Revision Date: May 5, 1999 Version 1.00 2 **Table** of Contents 1 Introduction 3 2 The Web Style
online.redwoods.cc.ca.us/instruct/darnold/StaffDev/Workshop/p_webeqman.pdf

[Metaclass Composability - Bouraqadi-Saadani, Ledoux, Rivard \(Correct\)](#)
Suppose A implements a foo method that sends **bar** to the class of the receiver. When foo is sent to with its sole instance (i.e.a class)ffl the **hierarchy** of the metaclasses is parallel to the **hierarchy** is organized into an architecture of several (meta)**levels** of abstraction. Each (meta)**level** describes and
ftp.emn.fr/pub/objet/publications/ecoop96.ps.gz

[On Partitioning Dynamic Adaptive Grid Hierarchies - Manish Parashar \(1996\) \(Correct\) \(22 citations\)](#)
of the DAGH in 5 such snapshots are listed in **Table** 1. Efficiency at a grid **level** refers to the and loadbalancing of the adaptive grid **hierarchy** to be performed cost-effectively. The run-time of logical locality, both across different **levels** of the **hierarchy** under expansion and contraction
www.cs.utexas.edu/users/dagh/.IPapers/hicss.ps

[Optimizing Metalization Patterns For Yearly Yield - Burgers Eikelboom Netherlands \(Correct\)](#)
that we arrive for yearly optimization at fewer bus **bars** and a much lower number of fingers. The total with in the next two subsections. Resistive losses **Table** 1 presents a compact overview of the different can be optimized for specific other illumination **levels**. In this paper we show that optimization for a
ftp.ecn.nl/pub/www/library/conf/ieee97/patterns.pdf

[Near-Critical Path Analysis of Program Activity Graphs - Alexander, al. \(1994\) \(Correct\) \(1 citation\)](#)
Computer, pp. 63-75, Sept. 1990. 22] D. Bailey, J. Barton, T. Lasinski, and H. Simon, ed.The near-critical **path** algorithms are summarized in **Table** I. **TABLE** I Worst-case complexities of descriptions of run-time events. IPS provides a **hierarchy** of statistical information based on a five
www.erc.msstate.edu/thrusts/ca/html/./publications/MASCOTncp.ps.gz

[A Hierarchy of Qualitative Representations for Space - Kuipers \(1996\) \(Correct\) \(16 citations\)](#)
(QR-96) Menlo Park, CA: AAAI Press, 1996. A **Hierarchy** of Qualitative Representations for Space foundation, and each abstracted from the **levels** below it. At the control **level**, the robot and its abstracted to a topological network of places and **paths**. Local metrical models, such as occupancy grids,
ftp.cs.utexas.edu/pub/qsim/papers/Kuipers-qr-96.ps.Z

[Hierarchical Hybrid Control: a Case Study - Godbole, Lygeros, Sastry \(1994\) \(Correct\) \(8 citations\)](#)
given the current technology. They are summarized in **table** 3.1. **Table** 1: Constraints on Actuators and of the plant model are used at each layer of the **hierarchy**. In the bottom layer the plant model is usually arranged in two (or more) layers [3, 4]Different **levels** of abstractions of the plant model are used at
robotics.eecs.berkeley.edu/~godbole/case.ps

Specifying Navigational Transformations in Hypermedia. A.. - Mere, Rossi (1996) (Correct)

1 Specifying **Navigational** Transformations in Hypermedia. A temporal

We are also studying the use of the Metatem tool (Barringer et al.95]to obtain an executable algorithm specify at a design, implementation-independent **level** which the desired transformations will be. In the www.egd.igd.fhg.de/veranstaltungen/workshops/egmm96/paper2.ps

Extending Locking Techniques to Improve Concurrent Database.. - Cesar Galindo-Legaria (Correct)

conflicts remains the same, and only the conflict **table** needs to be extended to include the new lock multigranularity locking, items are arranged in a **hierarchy** 1 We use the conventional terms for number of lock requests needed) mechanism for field-level locking. Locking of logical structures. Locking ftp.inria.fr/associations/ERCIM/research_reports/ps/0495R036.ps

Regular Expressions with Nested Levels of Back Referencing Form a .. - Larsen (1997) (Correct) (1 citation)

on Theory of Computing, pages 130 -141, 1979. 3] Barendregt, H. P.The Lambda Calculus: Its Syntax and with Nested **Levels** of Back Referencing Form a **Hierarchy** Kim S. Larsen Odense University y Abstract Regular Expressions with Nested **Levels** of Back Referencing Form a **Hierarchy** Kim S. ftp.imada.ou.dk/pub/papers/pp-1997/13.ps.gz

Integration of Reactive Navigation with a Flexible Parallel.. - Thomas Collins (1993) (Correct) (2 citations)

designs have emphasized connection across the **hierarchy**, as in the NASA/NBS standard reference model greater robustness is achieved, even when a higher **level** of deliberative behavior is added. From a first phase, each robot was to navigate the arena **cluttered** with obstacles without hitting anything, ftp.cc.gatech.edu/pub/people/arkin/web-papers/integration.ps.Z

Navigation Modelling in Hypermedia Applications - Daniel Schwabe (1994) (Correct)

hypermedia applications is the possibility of **navigational** access by the user. Although this type of ftp.inf.puc-rio.br/pub/docs/techreports/94_42_barbosa.ps.gz

A Design Framework for Hierarchical, Hybrid Control - Lygeros, Godbole, Sastry (Correct)

scheme will feature some form of multi **level hierarchy**, with lower **levels** dealing with local and each agent's resource utilization at a lower **level** and discrete controllers resolving inter-agent Office under grant DAAH 04-95-1-0588 and the **PATH** program, Institute of Transportation Studies, www.path.berkeley.edu/~lygeros/Publications/..Postscript/TAC_Design.ps

Learning of Compositional Hierarchies for the Modeling of Context .. - Pfleger (Correct)

with Teknowledge Federal Systems 137-1. Thanks to Barbara Hayes-Roth, Nils Nilsson, David Rumelhart, in letter perception, and an elegant new symbolic **hierarchy** generation algorithm called Sequitur. The Hierarchical compositional structure, in which high **level** entities represent aggregations of lower **level** www.stanford.edu/~kpfleger/copy/publications/CH.learning.ps.gz

Visualizing the World-Wide Web with the Navigational View.. - Mukherjea, Foley (1995) (Correct) (33 citations)

Visualizing the World-Wide Web with the **Navigational** View Builder Sougata Mukherjea, James D. Visualization) where the nodes are listed as a **table** of content of a book. Figure 11 shows a 3d tree Figure 7: A top view of the structure making the **hierarchy** formed by the abstraction layers apparent. The ftp.cc.gatech.edu/pub/groups/gvu/tr/95-09.ps.Z

Combining Navigational Planning and Reactive Control - Ali, Goel (1996) (Correct) (1 citation)

Combining **Navigational** Planning and Reactive Control Khaled S. Ali are insufficient for all classes of spatial worlds (**barring** toy or imaginary worlds, of course)But if organizes the neighborhoods in a space-subspace **hierarchy**. A more significant **pathway** connects more www.cc.gatech.edu/grads/a/Khaled.S.Ali/aaai96_workshop.ps.Z

A Three-Level Control Architecture For Autonomous Vehicle.. - Miura, Ito, Shirai (1997) (Correct)

to the exit. The averaged values are summarized in **Table** 1. With appropriate decisionmaking on the lane Systems Pp. 706-711, Boston, Ma, Nov. 1997. A Three-**Level** Control Architecture For Autonomous Vehicle www-cv.ccm.eng.osaka-u.ac.jp/members/jun/psfiles/itsc97.ps.gz

Behavior Hierarchy for Autonomous Mobile Robots.. - Tunstel, Lippincott.. (1997) (Correct) (3 citations)

higher fitness is evident for both GP and SSGP. **Table** 1 lists some quantitative details about the best Behavior **Hierarchy** for Autonomous Mobile Robots: Fuzzy-behavior which are collectively responsible for necessary **levels** of intelligence. Such a collection of rules can www.eece.unm.edu/grad/tunstel/papers/acesi.ps

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4	73	((siblings same (hides hiding conceal\$4 remov\$4) and (index indic\$4) with (tabs bar icon node level frame)) and (lowest child\$6)) and hierarch\$5	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:38
5	53	((((siblings same (hides hiding conceal\$4 remov\$4) and (index indic\$4) with (tabs bar icon node level frame)) and (lowest child\$6)) and hierarch\$5) and root and level	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:39
6	31	(((((siblings same (hides hiding conceal\$4 remov\$4) and (index indic\$4) with (tabs bar icon node level frame)) and (lowest child\$6)) and hierarch\$5) and root and level) and (brows\$4 navigat\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:48
7	122	index with (bar tab) and hierarch\$6 and (brows\$4 navigat\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:49
8	0	(index with (bar tab) and hierarch\$6 and (brows\$4 navigat\$4)) and siblings same (hides hiding conceal\$4 remov\$4) and (tabs bar icon node level frame)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:51
9	64	siblings same (hides hiding conceal\$4 remov\$4) and display\$4 with (tabs bar icon node level frame)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:51
10	12	siblings same (hides hiding conceal\$4 remov\$4) and display\$4 with (navigat\$4 index) with (tabs bar icon node level frame)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:55
11	63	siblings same (hides hiding conceal\$4 shown display\$4 remov\$4) and display\$4 with (navigat\$4 index) with (tabs bar icon node level frame)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:47
12	2	hierarch\$5 with level with organiz\$4 and clutter\$4 and small with display	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:44
13	50	5414809.URPN.	USPAT	2004/06/28 11:36

14	0	hierarch\$5 and levels and (tab bar) with index and clutter\$4 and small with display	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:45
15	6	hierarch\$5 and levels and (tab bar) with index and clutter\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:47
16	163	hierarch\$5 and levels and (tab bar) with (index indicies)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:49
17	639	siblings same (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4) and node	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:22
18	0	(hierarch\$5 and levels and (tab bar) with (index indicies)) and siblings same (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4) and node	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:48
19	0	hierarch\$5 and levels and (tab bar) with (index indicies) and siblings same (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:50
20	7	hierarch\$5 and levels and (tab bar) with (index indicies) and siblings	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:50
21	131	display\$4 with (level node indicies index bar tab) and siblings with (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4) and node	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:57
22	83	(display\$4 with (level node indicies index bar tab) and siblings with (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4) and node) and hierarch\$6 and select\$4 and (navigat\$4 brows\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:58
23	83	((display\$4 with (level node indicies index bar tab) and siblings with (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4) and node) and hierarch\$6 and select\$4 and (navigat\$4 brows\$4)) and (root sub-node lowest child)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:59
24	52	((display\$4 with (level node indicies index bar tab) and siblings with (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4) and node) and hierarch\$6 and select\$4 and (navigat\$4 brows\$4)) and root near5 (node bar tab)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:21
25	99	(travers\$4 travel\$4) with path and root near5 (node bar tab) and siblings	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:23
26	6	((travers\$4 travel\$4) with path and root near5 (node bar tab) and siblings) and (sub-node (sub near node))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:26

27	3	((travers\$4 travel\$4) with path and root near5 (node bar tab) and siblings) and (index indici\$4) with (tab bar frame) and represent\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:28
28	3	((travers\$4 travel\$4) with path and root near5 (node bar tab) and siblings) and (index indici\$4 nsvigat\$4) with (tab bar frame) and represent\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:28
29	16	((travers\$4 travel\$4) with path and root near5 (node bar tab) and siblings) and (index indici\$4 nsvigat\$4 select\$4) with (tab bar frame) and represent\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:43
30	2	6356920.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:20
31	2	5414809.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:20
32	243	siblings with (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4) and node	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:23
33	65	siblings with (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4) and node and (select\$4 travers\$4 travel\$4) with path	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:29
34	6	(siblings with (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4) and node and (select\$4 travers\$4 travel\$4) with path) and (show\$4 display\$4) with (bar tab) with (node index)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:25
35	9	(siblings with (hides collaps\$4 hiding conceal\$4 shown display\$4 remov\$4) and node and (select\$4 travers\$4 travel\$4) with path) and (show\$4 display\$4) with (bar tab) with (node index navigat\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:26
36	13	siblings with (hides collaps\$4 hiding conceal\$4 remov\$4) and node and (select\$4 travers\$4 travel\$4) with path	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:29